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Received: 11 November 2020 / Accepted: 30 June 2021 / Published online: 19 August 2021 © The Author(s), under exclusive licence to Springer Nature B.V. 2021

Abstract

Like civilization and technology, our understanding of the global water cycle has been continuously evolving, and we have adapted our quantifcation methods to better exploit new technological resources. The accurate quantifcation of global water fuxes and storages is crucial in studying the global water cycle. These fuxes and storages physically interact with each other, are related through the water budget, and are constrained by it. First attempts to quantify them date back to the early 1900s, and during the past few decades, they have received an increasing research interest, which is refected in the vast amount of data sources available nowadays. However, these data have not been comprehensive enough due to the high spatiotemporal variability of the global water cycle. Herein, we provide a comprehensive review of the chronological evolution of global water cycle quantifcation, the distinct data sources and methods used, and a critical assessment of their contribution to improving the spatiotemporal monitoring of the global water cycle. The chronology of global water cycle components shows that the uncertainty of fux estimates over oceans remains higher than that over land. Comparing the standard deviation and the interquartile range of the estimates from the 2000s onward with those from all the estimates (1905-2019), we can affirm that statistical variability has diminished in recent years. Moreover, the variability of ocean precipitation and evaporation estimates from the 2000 onward was reduced by more than 70% compared with earlier studies. These fndings advocate that the consistency of global water cycle quantifcation has been improved.

Keywords Global water cycle · Water budget · Multi-source quantifcation

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Article Highlights

- Global water cycle estimates into the perspective of a century of scientifc research
- Evolution of methods, observing systems, and models dealing with the global water cycle and water budgets
- Status quo of the global water cycle and its responses to global warming

1 Introduction

Water and its continuous circulation through its global cycle have played a fundamental role in sustaining life on Earth since its formation. The global water cycle is a complex phenomenon composed of several physicochemical processes such as condensation, evaporation, groundwater fow, infltration, percolation, plant uptake, precipitation, run-off, sublimation, transpiration, and water vapor transport (Allan et al. [2020](#page-23-0)), coupled with anthropogenic interactions like water withdrawals and soil moisture use for livestock, crop irrigation, and forestry (Abbott et al. [2019](#page-23-1)). The longstanding representation of the global water cycle's conceptual model has been limited to three variables, namely precipitation, evaporation and runof. Recently, this coarse representation has been partitioned to include the aforementioned sub-processes and their feedbacks. Our understanding of the global water cycle has been evolving over the years, and the methods we use to quantify hydrometeorological variables have adapted to exploit new technologies. Furthermore, the need to better estimate the components of the global water cycle has driven tailor-made techno-logical developments as well (e.g., satellite instruments; Hildebrand et al. [2003;](#page-26-0) Levizzani and Cattani [2019\)](#page-27-0).

Remote sensing data and model simulations complemented the traditional surfacebased measurements and ofered unprecedented coverage over previously inaccessible or unmonitored regions. Even though these advances provided vast data sources and aided to quantify water cycle components at multiple scales, their varying performances and uncertainties limit their applicability to global scale analyses (Brocca et al. [2019](#page-24-0)). Thus, the number of primary components used to quantify the global water cycle has not changed much. The most substantial diferences that arose with the inclusion of satellite data are the decomposition of total evaporation into evaporation over oceans and evapotranspiration over land (Dickinson [1984\)](#page-25-0), and the addition of total water storage (L'vovitch M, [1973](#page-28-0)). The above components represent the major inputs, outputs, and storage of the global water cycle. Hence, if we apply the mass conservation principle, we may write the water budget equation, which relates to these four components as follows.

$$
\Delta \text{TWS} = P - \text{ET} - Q \tag{1}
$$

where ΔTWS is the change in total water storage (as the sum of groundwater, soil moisture, and surface water such as river water, snow water, and water in lakes), *P* is precipitation, ET is evapotranspiration, and *Q* is the net water transport. The rest of the global water cycle processes are, to some extent, encompassed in these four components (Bengtsson [2010\)](#page-24-1). Inadvertently, aggregating global water cycle components to the most dominant ones also aggregates the underlying uncertainties of the minor components, which are overshadowed by the uncertainties of the major components with the available accuracy at the moment. Global water cycle quantifcation accuracy is further hindered by the inherent biases revealed in the frst attempts to unify multiple data sources for a single component due to the vast heterogeneity of algorithms and data used (Hegerl et al. [2018\)](#page-26-1).

Uncertainties in the quantifcation of global water cycle components are indispensable when attempting to close the water budget. We can express equation [1](#page-2-0) as:

$$
P - ET - Q - \Delta TWS = R \tag{2}
$$

where *R* is the budget residual, which in a closed budget equals to zero. Through the years, there have been various attempts to close the budget (Starr and Peixoto [1958](#page-31-0); Willmott et al. [1985](#page-32-0); Sheffield et al. [2009;](#page-31-1) Sahoo et al. [2011\)](#page-30-0). They have used different data sources and methods to minimize the residual, but non-closure of the water budget still prevails. Alternatively, rather than using budget closure as the performance metric, some research-ers prefer to look at runoff as a diagnostic flux to assess their results (Sheffield et al. [2009](#page-31-1)). Closing the water budget not only will improve our understanding of the global water cycle, but will necessarily lead to improvement of the accuracy of the data involved. Enhancing data accuracy is of critical importance for applications in climatology, hydrology, meteorology, and water resource management, to name a few.

To keep moving forward towards closure of the global water cycle, with more accurate data, it would be benefcial to assess previous achievements. Herein, we present a review of the chronological evolution of the paradigms regarding the global water cycle budget. We provide an in-depth recapitulation of the advancements in global water cycle quantifcation. In addition, we present a comparison between budgets reported in the literature, with highlights on the methods and data sources used. Using signifcant technological improvements as timeline reference milestones, we considered four epochs, namely Early Days of Hydrology, Model Simulations Period, Satellite Era, and Age of Big Data. Each epoch is characterized by its own accomplishments and challenges. Some of the latter were overcome in succeeding epochs and some prevailed up to the present. Despite data reaching unprecedented availability, detail, and coverage, the quest for robust quantifcation of the global water cycle remains.

2 Chronicle

2.1 Early Days of Hydrology

Studies of the global water cycle are as old as hydrology. In classical Greece, Plato and Aristotle philosophized that groundwater might be the component responsible for circulating water resources by connecting rivers and lakes. However, Marcus Vitruvius is most commonly credited to be the frst one to conceptualize the water cycle. In the frst century BCE, Vitruvius proposed a philosophical description of the water cycle that placed precipitation instead of groundwater as a critical component of water transport (Pollio [1648](#page-29-0)).

Vitruvius planted a seed that would later lead both, yet independently, during the sixteenth century, Leonardo da Vinci and Bernard Palissy into describing a water cycle with three principal components: precipitation, evaporation, and runoff (Palissy [1580;](#page-29-1) Pfister et al. [2009\)](#page-29-2). Therefore, equation [1](#page-2-0) was originally formulated as:

$$
P - E = Q \tag{3}
$$

where P is precipitation, E is evaporation, and Q is the runoff or exceeding precipitation. With this theoretical formulation, the scientifc community ventured into quantifying the above components during the seventeenth century. Pierre Perrault and Edmund Halley were among the pioneers that supplemented experimental science to hydrology with their research on catchment precipitation and evaporation, respectively (Brutsaert [2005\)](#page-24-2). John Dalton was the frst to quantify all three above-listed components for England and Wales, providing a comprehensive quantifcation of a water cycle and not just a single component of it (Dalton [1799](#page-25-1)).

With catchment scale quantifcation achieved, the next step was to aim for global-scale quantifcation. During the next years and up to the end of the 1960s, numerous studies, mainly coming from Germany and Russia, attempted to quantify the global water cycle. Baumgartner and Reichel [\(1972](#page-24-3)) surveyed the literature on global water cycle

Author	$P_{\rm L}$	ET	\mathcal{Q}	$P_{\rm O}$	E	P_{TOT}	$E_{\rm TOT}$
Brückner (1905)	122	97	25	359	384	481	481
Fritzsche (1906)	112	81	31	353	384	465	465
Schmidt (1915)	112	81	31	242	273	354	354
Wüst (1922)	112	75	37	267	304	379	379
Cherubim (1931)	112	75	37	334	371	446	446
Meinardus (1934)	99	62	37	412	449	511	511
Halbfaß (1934)	100	52	48	410	458	510	510
Wüst and Defant (1936)	99	62	37	297	334	396	396
Wundt (1938)	99	62	37	346	383	445	445
L'vovitch M. (1945)	107	71	36	412	448	519	519
Möller (1951)	99	62	37	< 324	361	≤ 423	≤423
Reichel (1952)	100	70	30	315	345	415	415
Wüst et al. (1954)	100	73	27	324	351	424	424
Budyko (1955)	100	66	34-38	370	408	470	474
Albrecht (1960)	100	67	33	378	411	478	478
Budyko (1963)	107	61	46-48	404	452	512	513
Mira (1964)	108	72	36	412	448	520	520
Nace (1968)	100	69	31	319	350	419	419
Kessler (1968)	100	60	40	410	450	510	510
Mather (1969)	106	69	37	382	419	488	488
L'vovitch (1970)	109	72	37	411	448	520	520
Budyko (1970)	107	64	43	412	455	519	519

Table 1 Modifed from Baumgartner and Reichel ([1972\)](#page-24-3) to exclude incomplete rows

All the fluxes are in 10^3 km³/year. P_L is precipitation overland, ET is evapotranspiration overland, Q is runoff, P_{O} is precipitation over oceans, E is evaporation over oceans, P_{TOT} is total global precipitation, and E_{TOT} is total global evaporation

quantifcation during the 1900s and added their fndings to the previous compilation by Reichel [\(1952](#page-30-2)), accounting for over 40 studies (Table [1](#page-4-0)). Over land, precipitation, range between (99 to 122) \times 10³ km³/year, evapotranspiration range between (52 to 97) \times 10³ km^3 /year, and runoff range between (25 to 48) \times 10³ km³/year. Over oceans, precipitation and evaporation range between $(242 \text{ to } 412) \times 10^3 \text{ km}^3/\text{year}$ and $(273 \text{ to } 458) \times 10^3 \text{ km}^3/\text{year}$ year, respectively. Note that evaporation and evapotranspiration have the most extensive ranges, presumably, because these values were derived from other measurements since, at the time, it was not possible to obtain direct observations. Even so, several reported fuxes are similar, if not identical, which may be caused by the fact that despite using diferent approximations or formulations, the initial data set used was the same. Over land precipitation estimates were derived from gauge and chart data, runoff estimates were derived from the river measurements by Marcinek ([1964\)](#page-28-7), and evaporation estimates were computed as the diference between precipitation and runof. Over oceans, heat balance maps, and climatological data for fixed locations constituted evaporation estimates, runoff is the same as overland because of atmospheric water balance (Rasmussen [1970\)](#page-30-3), and precipitation estimates were the difference between evaporation and runoff.

Due to the high variability in time and space of global water cycle components, ground station reports were not representative of the surrounding areas. Besides, it has been typical for developing countries not to possess a ground station network dense enough to monitor global water cycle components in those regions (Willmott et al. [1994\)](#page-32-5). Aware of the above, Baumgartner and Reichel ([1972\)](#page-24-3) introduced very strong yet somewhat arbitrary correction assumptions, and estimated the errors based on the biggest diference between the values compiled on their survey. Considering that the precipitation measured by rain gauges is smaller than the amount reaching the surface and there are diferent zonal climatic conditions overland, the authors suggest three diferent options to correct precipitation underestimation. They pointed out that the scenario selected is the most probable, yet no explanation is provided towards why that is. Correcting precipitation overland has a ripple efect because it is used to compute runoff, which is then used to compute precipitation over the oceans. Based on their assumptions, they report the quantifcation of the global water cycle had been achieved within a margin of ten percent relative error.

A decade later, Willmott et al. [\(1985](#page-32-0)) presented the first study with sufficient spatial coverage. Their study was based on temperature and precipitation observational data records from 13,332 globally distributed stations, and estimated terrestrial snow-cover, soil moisture, and evapotranspiration. Their work extended on previous regional studies over Africa (Mather [1962](#page-28-8)), Asia excluding U.S.S.R. (Mather [1963a\)](#page-28-9), U.S.S.R. (Mather [1963b\)](#page-28-10), Australia, New Zealand, and Oceania (Mather [1963c\)](#page-28-11), Europe (Mather [1964a](#page-28-12)), North America excluding USA (Mather [1964b\)](#page-28-13), USA (Mather [1964c\)](#page-28-14), and South America (Mather [1965\)](#page-28-15). The above cumulatively used only 8,565 stations from the same network Willmott et al. ([1985\)](#page-32-0) used on their study. Still, they had to use empirical equations and a revised version of the potential evapotranspiration method of Thornthwaite ([1948\)](#page-31-2) in order to derive snow-cover, soil moisture, and evapotranspiration from the temperature and precipitation observational data available. Willmott et al. [\(1985](#page-32-0)) did not report single values as annual averages, but presented their results in maps where it could be seen that annual mean evapotranspiration is approximately 173×10^3 km³/year over continental regions near the equator, 43×10^3 km³/year towards the poles, and below 43×10^3 km³/year across the Sahara, Arabia and Central Asia. Nonetheless, we know now, technological limitations and the lack of data sources place the fndings of the above discussed studies in a best-guess scenario only.

2.2 Model Simulations Period

In simple terms, General Circulation Models (GCMs) are a set of theoretical and empirical mathematical expressions that attempt to simulate climate's physical processes. They could be an atmospheric GCM, an oceanic GCM, or a coupled GCM. The frst atmospheric GCM was introduced by Norman Phillips [\(1956](#page-29-4)), and it opened the door to new opportuni-ties for global water cycle quantification (McGuffie and Henderson-Sellers [2001](#page-28-16)). Not long after, towards the end of the 1960s, the National Oceanic and Atmospheric Administration Geophysical Fluid Dynamics Laboratory developed the frst coupled GCM (Manabe [1969\)](#page-28-17). The basic structure of a GCM can be seen in Fig. [1.](#page-6-0) The GCM spatial domain is composed of 3D cells, whose horizontal grid is typically formed by latitude and longitude, and pressure levels determine the cell height. The number of physical processes considered and the complexity to which they are represented have continuously improved since the introduction of GCMs. Today's models further account for terrestrial vegetation and the carbon cycle with an explicit representation of biogeochemical processes—such models are referred to as Earth System Models or ESMs (Flato [2011;](#page-25-3) Collins et al. [2013](#page-25-4); Hurrell et al. [2013;](#page-27-2) Flato et al. [2014](#page-25-5); Otto-Bliesner et al. [2016](#page-29-5)).

Model simulations were initially driven exclusively by ground observations. Later on, satellite remote sensing, model reanalysis data sets, or diferent combinations of them were assimilated. Hydrological models revolutionized the quantifcation of the global water cycle by providing regular gridded data with global coverage as well as constant time steps. On top of that, both statistical and dynamical downscaling of GCMs and ESMs have evolved over the past decades to enable more reliable estimates (Tapiador et al. [2020](#page-31-3)). For example, the most recent release of the European Centre for Medium Range Weather Forecasts Reanalysis product (ERA-5), which is a reanalysis based on the European Centre for Medium-Range Weather Forecasts' Integrated Forecasting System (ECMWF's IFS) weather model, provides a 30 km global coverage with 137 atmospheric pressure levels

Fig. 1 Schematic structure of a General Circulation Model modifed from Bralower and Bice ([2012\)](#page-24-9)

capped at 80 km with uncertainty ranges reported at each level (Hersbach et al. [2020](#page-26-3)). Despite the exponential growth in computing power efficiency, many fundamental processes like radiative transfer, convection initiation, hydrometeor phase change, and cloud microphysics that occur between the sub-kilometer scale and the microscale (i.e., nine orders of magnitude less than current model resolutions) are parameterized, as they cannot be resolved at the model resolution. On that account, while GCMs and ESMs provide global coverage of water cycle components, their spatial and temporal resolution is still relatively coarse, hindering validation attempts.

Model simulations further changed global water cycle quantifcation by providing more robust formulations towards the estimation of evapotranspiration. The bucket model developed by Budyko ([1961\)](#page-24-10) was implemented for the evapotranspiration scheme used in the frst coupled GCM (Manabe [1969\)](#page-28-17). This scheme oversimplifed the physical processes sur-rounding evapotranspiration (Fig. [2\)](#page-7-0); nevertheless, its results were not significantly different from much more complex formulations attempted in contemporaneous GCMs (Carson [1982\)](#page-24-11). In the aforementioned scheme, evapotranspiration depends on potential evaporation, soil water content, feld capacity (defned as the amount of soil moisture or water content held in the soil after excess water has drained away and the rate of downward movement has decreased), and water holding capacity (Carson [1982\)](#page-24-11). Federer et al. [\(1996](#page-25-6)) compared fve surface-independent and four surface-dependent potential evapotranspiration approximation schemes in models, and their results suggest that, at that time, none of the methods signifcantly difer from each other for most surface types. Still, the authors point out that the Penman-Monteith (Monteith and Unsworth [2013](#page-28-18)) and Shuttleworth & Wallace (Shuttleworth and Wallace [1985](#page-31-4)) methods might pose as the most comprehensive for globalscale analysis, a hypothesis that was later confrmed for Penman-Monteith (Wang and Dickinson [2012\)](#page-32-6).

The coupled GCM introduced by Manabe [\(1969](#page-28-17)) simulated average values of 93.4 \times 10³ km³/year overland precipitation, 69.5×10^3 km³/year evapotranspiration, 23.9×10^3 km³/ year runoff, 359.3×10^3 km³/year over ocean precipitation, and 429×10^3 km³/year evapo-ration. In recent years, Haddeland et al. [\(2011](#page-26-4)) compared 11 model simulations for the period 1985-1999 (Table [2](#page-8-0)). Observation-based data for global precipitation overland had an average value of 126×10^3 km³/year, simulated evapotranspiration, and runoff mean values range between (60 to 85×10^3 km³/year and (42 to 66) $\times 10^3$ km³/year, respectively. Note that Manabe's evapotranspiration estimate is the only fux within the values reported by Haddeland et al. [\(2011](#page-26-4)). Besides, the later estimates are within the range for annual averages reported by Baumgartner and Reichel [\(1972](#page-24-3)), hinting that despite the substantial uncertainties and approximations, the values reported in the previous period were not that far from the current ones.

Model simulations did represent a new data source with seeming advantages over observations like the ability to generate global coverage data and perhaps more revolutionary to forecast, predict, and project. Nevertheless, once again, the scientifc community relied heavily on observational data because it was crucial for model calibration and validation. Consequently, this novel opportunity to research global water cycle variability and its response to global warming further stressed the need for better observation-based measurements and more accurate quantifcation of the cycle components.

2.3 Satellite Era

Shortly after the introduction of climate models (Phillips [1956\)](#page-29-4), the Television Infrared Observation Satellite (TIROS-1 or TIROS-A) became the frst weather satellite successfully launched in 1960, and so it began the satellite era (NOAA [1987](#page-29-6)). Barnes and Bowley [\(1968](#page-24-14)) proved the efectiveness of satellite observations in hydrology when they published their fndings on snow cover mapping over the Missouri and Upper Mississippi River basins. Thereafter, several satellite missions made it into orbit, among the most notable, we may mention the National Aeronautics and Space Administration (NASA) Earth Observing System (EOS) missions. Based on their orbits, satellites could be grouped into two major groups, either geosynchronous orbit (GEO) or polar orbit. Many of the satellites involved in the EOS missions have a nearly polar orbit. Polar-orbit satellites move around the Earth in a Sun-synchronous orbit so that the overpass occurs at the same local time every day, taking around 100 minutes to complete an orbit. These satellites overpass the equator at the same local solar time each day. Satellite sensors could be active or passive, and it is not uncommon for both to be onboard the same satellite. For example, the Tropical Rainfall Measuring Mission (TRMM) Microwave Imager (TMI), a passive sensor, and the Precipitation Radar (PR), an active sensor, were onboard the TRMM satellite. Regarding satellites and missions of particular interest for global water cycle quantifcation, we have the TRMM (Hufman et al. [2007](#page-26-9)) and the Global Precipitation Measurement (GPM) (Hufman et al. [2015](#page-27-5)) for precipitation, the Moderate Resolution Imaging Spectroradiometer (MODIS) for evapotranspiration (Mu et al. [2011](#page-28-20)), and the Gravity Recovery and Climate Experiment (GRACE) for total water storage (Tapley et al. [2004](#page-31-6)). There is no specific instrument nor mission dedicated solely to runoff yet (Hong et al. [2007](#page-26-10)). However, runoff could be derived from other satellite observations, for instance, TRMM precipitation (Hufman et al. [2007](#page-26-9)), and MODIS land cover (Friedl et al. [2002](#page-25-10)) using the Natural Resources Conservation Service (NRCS) runoff curve number method (Cronshey [1986;](#page-25-11) Burges et al. [1998\)](#page-24-15).

Satellite observations complemented the traditional surface measurements and ofered unprecedented observational coverage on a global scale (McCabe et al. [2017\)](#page-28-21). The Defense Meteorological Satellite Program (DMSP) near-polar orbiting satellites have been key providers of data over the oceans since 1987 (Dubach and Ng [1988\)](#page-25-12). Onboard their satellites, the most notable instruments are the Special Sensor Microwave Imager (SSM/I) (Hollinger [1991\)](#page-26-11) and its successor, the Special Sensor Microwave Imager Sounder (SSMIS) (Kunkee et al. [2008\)](#page-27-6). These passive microwave radiometers provide measurements used to derive data on surface wind speed, atmospheric water vapor, cloud liquid water, and rain rate, which are critical to quantifying the global water cycle (Robertson et al. [2014\)](#page-30-5). Furthermore, various present-day models and reanalysis products assimilate satellite observations (Van Dijk et al. [2011\)](#page-32-7). Nonetheless, like for GCMs, ground observations are crucial for satellite data validation. Notwithstanding, the number of ground stations worldwide has been declining since the 1970s (Walker et al. [2016](#page-32-8)). It was not before Trenberth et al. [\(2007](#page-31-7)) that the availability of observational and modeled data to quantify the global water cycle was exploited. A year prior, Oki and Kanae ([2006\)](#page-29-7) presented a quantitative synthesis of the global water cycle. Instead of estimating the budget, they made a compilation of individual studies to stress the importance of global water cycle quantifcation and further assessment to manage renewable freshwater resources properly. This concern has been in the minds of the scientifc community for quite some time now (Falkenmark and Lindh [1974](#page-25-13)). The budget assessments by Trenberth et al. and Oki & Kanae are held in high regard and are often used as a sort of validation reference (Rodell et al. [2015](#page-30-6)).

Oki and Kanae [\(2006](#page-29-7)) addressed the availability of renewable freshwater resources for human consumption within the global water cycle. The authors stressed that freshwater availability would be better assessed by fuxes than by storages because water is a circulating resource. Also, given the high variability of the water cycle in time and space, water stress is not a problem of how much water is available but a matter of when and where it is available (Postel et al. [1996](#page-29-8)). To better represent their research, they synthesized previous estimates of global water cycle fuxes and storages (Korzoun [\(1978](#page-27-7)), Shiklomanov ([1998\)](#page-31-8), Dirmeyer et al. [\(2006](#page-25-14)), and Oki [\(2006](#page-29-9))). By doing so, they also presented a much more comprehensive mean state of the global water cycle. Their results showed overland precipitation of 111×10^3 km³/year, evapotranspiration of 65.5×10^3 km³/year, and runoff of 45.5×10^3 km³/year. Moreover, precipitation is divided into rainfall and snowfall, plus the fuxes are allocated to diferent terrains or land uses. Over oceans, precipitation was 391×10^3 km³/year and evaporation was 436.5×10^3 km³/year.

Trenberth et al. ([2007\)](#page-31-7) used different data sources to quantify the global water cycle and its components. Three data sets were selected for precipitation, the Global Precipitation Climatology Project (GPCP v2; Adler et al. [2003](#page-23-5)), the University of East Anglia Climatic Research Unit time-series (CRU TS 2.1; Mitchell and Jones [2005](#page-28-22)), and the PRE-Cipitation REConstruction over Land (PREC/L; Chen et al. [2002\)](#page-24-16). Evapotranspiration was simulated using the Community Land Model version 3 (CLM3; Bonan et al. [2002](#page-24-17); Qian et al. [2004](#page-29-10)), which was forced using a combined PREC/L and GPCP precipitation data set. Surface plus subsurface runoff was derived from two climatic water balance estimates (evapotranspiration minus precipitation), the frst from the European Centre for Medium Range Weather Forecasts Reanalysis 45 year product (ERA40; Uppala et al. [2005\)](#page-31-9) using the methods described by Trenberth and Guillemot [\(1998](#page-31-10)), and the second using evapotranspiration from CLM3 and GPCP precipitation. Additionally, the authors relied on previous work for some components of the global water cycle like surface runof (Dai and Trenberth [2002\)](#page-25-15), ice volumes (Houghton et al. [2001\)](#page-26-12), soil moisture (Webb et al. [1993](#page-32-9)), and groundwater (Schlesinger [2005\)](#page-30-7). It was common for prior studies to cite values that, in

return, cite another and so on. Unlike them, the authors documented, and traced back as far as possible, the origins of the values used. They reported 113×10^3 km³/year overland precipitation, 73×10^3 km³/year evapotranspiration, 40×10^3 km³/year runoff, 373×10^3 km³/ year over ocean precipitation, and 413×10^3 km³/year evaporation.

It is important to note that satellite data records are recently of sufficient time frame lengths and with methods "mature" enough to develop meaningful global water cycle climatology records that can provide information on its components mean state and variability (Schlosser and Houser [2007](#page-30-8); Robertson et al. [2014](#page-30-5)). Exploiting the increasing avail-ability and maturity of satellite products, Sheffield et al. [\(2009](#page-31-1)) addressed the feasibility of closing the water budget, relying solely on satellite-based products. They combined the TRMM Multi-satellite Precipitation Analysis (TMPA; Hufman et al. [2007\)](#page-26-9) and the Climate Prediction Center morphing method (CMORPH; Joyce et al. [2004](#page-27-8)) products for precipitation, the University of Colorado GRACE time series (CSR RL04; Wahr et al. [1998](#page-32-10)) for total water storage, and they derived evapotranspiration from Aqua satellite data using the Penman-Monteith revised formulation proposed by Mu et al. ([2007\)](#page-28-23). Then they evaluated their fndings over the Mississippi River basin comparing their runof estimates, computed as the budget residual, with ground observations. Their results indicate that the data products selected do not close the budget because the computed runoff is greatly overestimated compared to ground measurements. The authors suggest that further improvement of satellite-based products may reduce the residual and suggest multi-source data merging as a complementary means to achieve budget closure.

2.4 Age of Big Data

In this day and age, we have transitioned from minimal data coverage and sources into a widely heterogeneous abundance. In contrast to the continuous decline in the number of ground stations, satellite-based and model-derived data products have proliferated. However, while some components of the global water cycle have multiple products to choose from (e.g., precipitation), others do not (e.g., total water storage). Some products assimilate or calibrate against ground station data to improve their performance (Rudolf and Schneider [2005](#page-30-9)); others implemented machine learning processing to do so (Hong et al. [2004](#page-26-13)). It is not uncommon to fnd performance comparisons between products in the literature, evincing large diferences in the magnitude and the variability of the estimates (e.g., as much as 300 mm/year diference between precipitation data sets; Sun et al. [2018](#page-31-11)). In their global comparison of 30 data sets at multiple spatiotemporal scales, Sun et al. [\(2018](#page-31-11)) found that, in general, variability from reanalysis data sets is more substantial than that from other data sources. Conversely, we can see that no single data set performs the best in all regions and at all scales. Aware of that fact, some studies did not look for the best individual data set, but the best combination of data sets towards budget closure of the water cycle over one (Azarderakhsh et al. [2011\)](#page-23-6) or multiple basins (Lorenz et al. [2014\)](#page-28-24). It should be pointed out that the above studies' success metric was not budget closure itself, but validation versus in situ runoff instead.

The paradigm of quantifying the global water cycle is steadily shifting from identifying the best data source per water cycle component into developing the best way to merge data from various sources to complement each other. Various integration methodologies have emerged, among the most widely used ones are: Bayesian model averaging, constrained linear regression, neural networks, optimal interpolation, and simple weighting (Bishop [1995;](#page-24-18) Hoeting et al. [1999;](#page-26-14) Rodgers [2000;](#page-30-10) Aires et al. [2004\)](#page-23-7). Also, post-processing closure methodologies, which distributed the budget residual R among the components based on each component's uncertainties, explored Monte Carlo applications and Kalman flter variations (Pan and Wood [2006](#page-29-11); Munier and Aires [2018\)](#page-29-12). Specifcs vary from method to method, but, in general, combining diferent data sets consists of three steps. These steps are an initial assessment of the products to be combined, followed by the integration of the products, and fnally, budget closure post-processing.

Data integration is not a new concept nor the methods mentioned above, but its implementation altogether with closure constraints into the quantifcation of the water cycle is. Sahoo et al. [\(2011](#page-30-0)) used 16 data sets (eight for precipitation, six for evapotranspiration, one for runof, and one for total water storage) applying simple weighting integration over ten basins across the globe, determining water cycle budget non-closure between $5 - 25\%$. Likewise, Pan et al. [\(2012](#page-29-13)) used eight data sets (four for precipitation, two for evapotranspiration, one for runoff, and one for total water storage) in 32 different basins. The authors focused on describing the uncertainty contribution of each component rather than focusing on budget closure, and found that, in general, most of the closure error comes from evapotranspiration.

To date, only a few studies have adopted multi-source data integration at the global scale (Rodell et al. [2015](#page-30-6); Zhang et al. [2016;](#page-32-11) Munier and Aires [2018\)](#page-29-12). The diferences between studies and their results reside either on the data sets selected or in the post-processing. Rodell et al. [\(2015](#page-30-6)), using six data sets (one for precipitation, three for evapotranspiration, one for runof, and one for total water storage; Table [3](#page-12-0)), reported a non-closure residual of less than 10%. The authors adopted the variational data assimilation algorithm of L'Ecuyer and Stephens [\(2002](#page-27-9)) and adjusted it to optimize the global water cycle budget closure at the annual scale. They reported $(116.5 \pm 5.1) \times 10^3$ km³/year overland precipitation, $(70.6 \pm 5.0) \times 10^3$ km³/year evapotranspiration, $(45.9 \pm 4.4) \times 10^3$ km³/year runoff, $(403.5 \pm 22.2) \times 10^3$ km³/year over ocean precipitation, and $(449.5 \pm 22.2) \times 10^3$ km³/ year evaporation. Note that the estimates reported by Oki and Kanae [\(2006](#page-29-7)) and Trenberth et al. ([2011\)](#page-31-12) lie within the above fndings with the only two exceptions of overland precipi-tation from Oki and Kanae [\(2006](#page-29-7)) and runoff from Trenberth et al. [\(2011](#page-31-12)).

Zhang et al. ([2016\)](#page-32-11), using 14 data sets (five for precipitation, six for evapotranspira-tion, one for runoff, and two for total water storage; Table [4\)](#page-13-0), assessed the effect of different data sources in the estimation of the water cycle and its budget closure. By removing/ replacing in situ observations, reanalysis products, model simulations, or satellite products before data integration, the authors observed that removing non-satellite sources worsens

Data source	Variable	Reference(s)
GPCPv2.2	P	Adler et al. (2003); Huffman et al. (2009)
Princeton ET	ET	Vinukollu et al. (2011b)
MERRA and MERRA-Land	ET	Rienecker et al. (2011) ; Bosilovich et al. (2011) ; Reichle (2012)
GLDAS	ET	Rodell et al. (2004)
University of Washington runoff	0	Clark et al. (2015)
CSR RL05	ATWS	Chambers and Bonin (2012); Johnson and Chambers (2013); Tapley et al. (2004)

Table 3 Compiled from Rodell et al. [\(2015](#page-30-6)). *P* is precipitation, ET is evapotranspiration, *Q* is runof, and *𝛥*TWS is changes in total water storage

closure errors. Furthermore, as for satellite data sets, they indicate that budget closure error depends on the use of satellite-only data sets or satellite-gauge combined data sets. Regardless of the combination of data sets, the budget could not be closed and, thus, a constrained Kalman filter was used, as developed by Sahoo et al. [\(2011](#page-30-0)). They reported a non-closure residual that ranges between 7.6 – 10.4% when using satellite products that lack gaugebased corrections, which is reduced to $4.2 - 9.0\%$ when using gauge-corrected satellite products.

Munier and Aires [\(2018](#page-29-12)) integrated 12 data sets (four for precipitation, three for evapo-transpiration, one for runoff, and four for total water storage; Table [5](#page-13-1)) over 11 basins to test a budget closure correction model. The authors defne the Calibration Index for Closure (CIC), which depends on the values of precipitation minus evapotranspiration (*P* − ET) and the Normalized Diference Vegetation Index (NDVI), and based on the CIC values,

assigned the basins into one of four classes. Then the closure correction model is calibrated to each basin using the corresponding CIC class, and it optimizes budget closure for the fuxes one at the time. While no absolute values are reported, the authors describe how this novel method reduced non-closure residuals by 26% of the value it would have using constrained Kalman flter post-processing.

In the above-mentioned studies, there is a methodological consensus to use simple weighting when integrating data from various sources. This is in good agreement with Aires ([2014\)](#page-23-8) who compared the performance of diferent integration methods, and reported that simple weighting is the most suitable one. Simple weighting ofers a straightforward formulation, and more elaborate methods do not ofer enough improvement on results to justify the increased complexity they carry along. The assumption for the simple weighting method is that the errors associated with the diferent products are Gaussian (zero-mean) and independent. However, there might be cases that this assumption may not hold, especially for gauge-based data products, and the dependence among products will cause an underestimation of the error associated with the integrated data set. The combined data set for a given component of the global water cycle $(P, ET, Q, or \Delta TWS)$ is equal to:

$$
x = \sum_{i=1}^{n} w_i x_i \tag{4}
$$

where x is the combined data set for the single component of the global water cycle being integrated, x_1 , x_2 , x_3 , ..., x_n are the different products considered, w_i is the associated weight of product x_i and is defined as:

$$
w_i = \frac{(\bar{x} - x_i)^{-2}}{\sum_{j=1}^{n} (\bar{x} - x_j)^{-2}}
$$
(5)

where \bar{x} is the arithmetic mean of the *n* data products considered, and $(\bar{x} - x_i)^2$ is defined as the error variance. That is to say, the weight associated to each product is proportional to the inverse of its error variance. Finally, the error associated to the combined data set *x* is:

$$
e_x = \frac{1}{\sum_{i=1}^{n} (\bar{x} - x_i)^{-2}}
$$
(6)

3 Status Quo et Verisimile Futurum

It might have been noticed that the chronology of global water cycle quantifcation does not follow a linear timeline. The epochs started at diferent points in time without replacing the one before. Each epoch did not only continue to develop, but just like global water cycle components, they interacted with each other in a feedback loop. A convergence point is the fact that model simulations and satellite-based measurements depend upon ground observations either for validation or calibration. The latest epoch, the age of big data, does not intend to merge all the previous into one, but to exploit the various data sources stemming from them to generate the most accurate estimates possible. Therefore, we should keep working on the continuous improvement of ground measurements, model simulations, and satellite observations, which will inherently improve their integration. Abbott et al. [\(2019](#page-23-1)) provided one of the most recent descriptions of the global water cycle. Analogously to

Fig. 3 The Water Cycle. Credit: Howard Perlman, United States Geological Survey (USGS)

Oki and Kanae [\(2006](#page-29-7)), the authors did not quantify the global water cycle components themselves but synthesized data from the literature. The authors did not aim to quantify the components of the global water cycle but to assess its correct representation. To do so, they compiled over 464 diagrams (e.g., Fig. [3\)](#page-15-0) and estimates from over 80 studies. Human interaction was absent in approximately 85% of the diagrams, highlighting the omission of the non-negligible anthropogenic component of the water cycle. In addition, the authors stress the necessity to represent seasonal and interannual variability of the global water cycle fuxes and storages in diagrams because the general understanding of temporal variability of the global water cycle is absent in the collective consciousness (Cardak [2009\)](#page-24-22). Within the studies, not all of them reported estimates for all components of the global water cycle. The synthesis resulted in the following estimates: overland precipitation 110×10^3 km³/ year, evapotranspiration 69 \times 10³ km³/year, and runoff 46 \times 10³ km³/year; over oceans, precipitation 380 \times 10³ km³/year and evaporation 420 \times 10³ km³/year.

Herein, building upon the previous compendium done by Baumgartner and Reichel ([1972\)](#page-24-3), we surveyed the recent literature, and to the best of our knowledge, compiled all the diferent estimates of global water cycle components available in peer review journals that at least report the average annual fuxes for the terrestrial or oceanic water cycle (Table [6\)](#page-16-0). Since 2010 it has become more common for studies to address only the terrestrial water cycle (e.g., Van der Ent et al. [2010;](#page-32-15) Haddeland et al. [2011;](#page-26-4) Jasechko et al. [2013;](#page-27-14) Zhang et al. [2018](#page-32-16)). On the other hand, ocean salinity measurements are being exploited to study the oceanic branch of the water cycle (Durack [2015](#page-25-17)), yet there are very few studies focusing solely on the oceanic water cycle (e.g., Syed et al. [2010;](#page-31-17) Robertson et al. [2014;](#page-30-5) Gutenstein et al. [2021\)](#page-26-17). Inspecting the chronology of global water cycle flux annual average estimates over land and over oceans, it is safe to state that uncertainty estimates associated with fluxes over oceans is higher than that over land (Figs. $4(a)$ $4(a)$) and $4(b)$). Comparing

Table 6 All the fluxes are in 10^3 km³/year. P_L is precipitation overland, ET is evapotranspiration overland, Q is runoff, P_{Ω} is precipitation over oceans, *E* is evaporation over oceans, P_{TOT} is total global precipitation, and E_{TOT} is total global evaporation

Author	$P_{\rm L}$	ET	ϱ	P_{Ω}	E	$P_{\rm TOT}$	$E_{\rm TOT}$
Manabe (1969)	93.4	69.5	23.9	359.3	429	452.7	498.5
Baumgartner and Reichel (1972)	100	65	35	383	418	483	483
Falkenmark and Lindh (1974)	114	73	41	412	453	526	526
Speidel and Agnew (1982)	111	71	39.7	385	425	496	496
NRC (1986)	107	71	36	398	434	505	505
Van der Leeden (1990)	100	70	39.6	320	350	420	420
Gleick (1993)	119	72	47	458	505	577	577
Schmitt (1995)	110.4	69.4	41	384.7	425.7	495.1	495.1
Shiklomanov (1998)	119	74.2	42.7	458	502.8	577	577
Oki (1999)	115	75	40	391	431	506	506
Oki and Kanae (2006)	111	65.5	45.5	391	436.5	502	502
Schlosser and Houser (2007)	103.5	63	40.5	376	417	479.5	480
Trenberth et al. (2007)	113	73	40	373	413	486	486
Lim and Roderick (2009)	113	78.8	34.1	417.7	451.8	530.7	530.8
Syed et al. (2010)			36.1	374.2	409.2		
Van der Ent et al. (2010)	117	82	35				
Chapin III et al. (2011)	110	71	40	385	425	495	496
Haddeland et al. (2011)	126	72.5	54				
Trenberth et al. (2011)	114	74	40	386	426	500	500
Jasechko et al. (2013)	110	72.7	37.3				
Durack (2015)	110.4	85.1	39.4	384.7	410	495.1	495.1
Rodell et al. (2015)	116.5	70.6	45.9	403.5	449.5	520	520.1
Schneider et al. (2017)	117.6	71.8	45.8	386	431.8	503.6	503.6
Zhang et al. (2018)	114.7	68	46.6				
Abbott et al. (2019)	110	69	46	380	420	490	489

the standard deviation and the interquartile range of the estimates from Oki ([1999\)](#page-29-14) onward with the ones from all the estimates (1905-2019), we can affirm that variability has diminished in recent years (Figs. $4(c)$ $4(c)$ and $4(d)$ $4(d)$). Moreover, the variability of ocean precipitation and evaporation was reduced by more than 70%. These fndings advocate that the consistency of the estimates has been improved.

Despite our survey compiling estimates available in the literature rather than presenting a more "traditional" estimates' time series, we observe an increasing trend in the global water cycle fuxes annual average as the year of publication progresses (Fig. [5](#page-17-1)). We should remark that the years listed correspond to the publication date and do not necessarily refect on the data sets' reference period used by the authors therein. Hence, our observations are of qualitative and not quantitative character. An increasing trend in global water cycle fuxes, commonly referred to as intensifcation, is often attributed to global warming; however, the processes that drive the global water cycle's response are yet to be fully understood (Allan et al. [2020\)](#page-23-0). Take note that these estimates are global and do not describe changes in the water cycle at diferent smaller scales. On top of that, we should not assess these results conclusively because most studies used diferent data sources and diferent

Fig. 4 Probability density distribution of global water cycle fuxes from Tables [1](#page-4-0) and [6](#page-16-0). The dashed line represents the mean value of each fux. (a) Overland fuxes where *P* is precipitation, ET is evapotranspiration, and Q is runoff. (b) Over ocean fluxes where P is precipitation and E is evaporation. (c) Same as (a) but only for Table [6](#page-16-0). (d) same as (b) but only for Table [6](#page-16-0)

Fig. 5 Chronological estimates of global water cycle fluxes over land in 10^3 km³/year. *P* is precipitation, ET is evapotranspiration, and *Q* is runoff. The years listed correspond to the publication date and do not necessarily refect the data sets' reference period used by the authors

Fig. 6 Chronological estimates of global water cycle fluxes over oceans in 10³ km³/year. *P* is precipitation and *E* is evaporation. The years listed correspond to the publication date and do not necessarily refect the data sets' reference period used by the authors

methods at diferent development stages, as discussed in the previous section. For example, if we were to look only at Table [6](#page-16-0) entries in Fig. [6](#page-18-0) (from Baumgartner and Reichel [\(1972](#page-24-3)) onward), we would not be able to clearly discriminate a trend from the variability present

Fig. 7 Chronological estimates of the evaporative index. This is defned as the ratio between evapotranspiration and precipitation overland (ET/*P*). The years listed correspond to the publication date and do not necessarily refect the data sets' reference period used by the authors

in those estimates. Moreover, suppose we were to omit the estimates reported between Van der Leeden ([1990\)](#page-32-17) and Shiklomanov ([1998\)](#page-31-8), there seem to be minor oscillations around an overall fat trend, attesting the narrative is dependent on the data being observed. Latch onto the ratio between evapotranspiration and precipitation over land, also known as the Evaporative Index (ET/*P*; Fig. [7\)](#page-18-1), and it is interesting to see how, despite some clear multiannual oscillations, there seems to be no sharp trend. The Evaporative Index is the fraction of available water consumed by evapotranspiration (Budyko [1974\)](#page-24-24), and assuming no signifcant change in total water storage, its residual (1− ET/*P*) could be inferred as the fraction that turns into available freshwater. This, at least on paper, would suggest global freshwater availability has not diminished on average.

Through the previous sections, we have described how our understanding of the global water cycle has been evolving over the years as we exploit novel technologies and methods to quantify the components of the global water cycle more accurately. Accordingly, to assess future changes in the global water cycle and its response to global warming, we should study both past shifts documented in observational records and possible changes predicted by model simulations. While there are inherent fuctuations in the global water cycle, some of them are driven by natural phenomena like variations in the Sun and volcanic eruptions (e.g., the year without a summer; Stommel and Stommel [1979](#page-31-19)), and anthropogenic activities. The latter exerts a continuously increasing infuence directly via interference with land surface and water consumption, and indirectly via greenhouse gases and aerosols emissions (Abbott et al. [2019](#page-23-1)). The nature of the driver and the spatial scale they exercise domain over alter key water cycle characteristics, e.g., precipitation frequency, intensity, or duration (Pendergrass and Hartmann [2014\)](#page-29-16).

Concurrently, model simulations predicted that global mean precipitation would rise in response to $CO₂$ doubling (Mitchell et al. [1987](#page-28-25)). The relationship between climate and water cycle caught the attention of both climatic and hydrological communities (Chahine [1992b;](#page-24-25) Loaiciga et al. [1996\)](#page-27-16). Models and the relationship between climate and water cycle are continuously evaluated in the Assessment Reports of the Intergovernmental Panel on Climate Change (IPCC; Collins et al. [2013;](#page-25-4) Flato et al. [2014](#page-25-5)). The Clausius–Clapeyron expression for the saturation vapor pressure establishes that at temperatures typical of the lower troposphere, the water holding capacity increases by about 7% for each 1K increase in temperature. It is safe to assume that an increase in lower-tropospheric water vapor will lead to a chain reaction afecting the entire global water cycle. The poorly understood response of the global water cycle resulted in two main hypotheses: the "changing character of precipitation" and the "dry gets drier, wet gets wetter". The former shows that the increase in global mean precipitation will be unevenly distributed in precipitation events (Trenberth et al. [2003](#page-31-20)). Heavy or extreme rainfall will become more frequent, while light or moderate precipitation will decline. The latter suggests that the increased vertical gradient of atmospheric water vapor would ofset atmospheric wind convergence in the tropics making wet regions wetter and dry regions drier (Roderick et al. [2014](#page-30-17)). Both hypotheses are today under vigorous debate (Held and Soden [2006;](#page-26-19) Seager et al. [2010;](#page-30-18) O'Gorman and Muller [2010](#page-29-17); Greve et al. [2014](#page-26-20); Roderick et al. [2014;](#page-30-17) Byrne and O'Gorman [2015;](#page-24-26) Kumar et al. [2015](#page-27-17); Salzmann [2016](#page-30-19); Skliris et al. [2016;](#page-31-21) Wang et al. [2017;](#page-32-18) Markonis et al. [2019;](#page-28-26) Allan et al. [2020](#page-23-0)).

Global precipitation and evapotranspiration, however, are further associated with Earth's energy budget rather than the Clausius-Clapeyron equation (O'Gorman et al. , [2012](#page-29-18); Roderick et al. , [2014](#page-30-17)). Model simulations report that in response to global warming, global precipitation and evapotranspiration, independently of climate forcing, would increase constrained by Earth's energy budget to an expected rate between 2-3%/K (Samset et al. [2018](#page-30-20)).

Precipitation's response to global warming, also known as apparent hydrological sensitivity, comprises a fast reaction proportional to radiative forcings and a slow temperaturedependent response to the radiative forcings (Bala et al. [2010\)](#page-23-9). Across multiple model simulations, precipitation increases with global warming are generally suppressed over land compared to the global mean $(0.8-2.4\%/K)$ vs. 2.3-2.7%/K), a behavior partly expected due to limitations on moisture convergence product of the more signifcant warming over land than oceans (Richardson et al. [2018](#page-30-21)). Considering that global precipitation's response to global warming is slower than the response of atmospheric water vapor, atmospheric water vapor lifetime must increase to reconcile these diferent response rates (Hodnebrog et al. [2019\)](#page-26-21). By doing so, regional characteristics of precipitation such as seasonal duration, frequency, and intensity are altered (Pendergrass [2018\)](#page-29-19).

As atmospheric water vapor content increases and its lifetime prolongs, the increased horizontal moisture transport induces an intensifcation of precipitation minus evapotranspiration patterns. Over the continents, precipitation minus evapotranspiration is positive and accounts for the freshwater fux from the atmosphere to the surface, whereas over the ocean, precipitation minus evaporation is negative and represents the freshwater fux from the oceans to the atmosphere. In dry regions, where evapotranspiration is constrained by water availability, changes in precipitation minus evapotranspiration will be mainly credited to precipitation changes (Roderick et al. [2014](#page-30-17)). Precipitation minus evapotranspiration over land can be negative during dry seasons or extended drought periods (Kumar et al. [2015](#page-27-17)). Given that evapotranspiration is a compound flux of evaporation and transpiration, the response of vegetation to global warming and increased $CO₂$ concentrations in the atmosphere will also determine the characteristics of regional precipitation minus evapotranspiration patterns. Besides, over land, we cannot neglect anthropogenic activities like irrigation, land-use change, deforestation, urbanization, and water withdrawals, among others that directly alter precipitation minus evapotranspiration regimes. On this account, we can expect several factors like topography, atmospheric circulation, anthropogenic tampering, and vegetation response to generate diferent and complex water cycle responses to global warming.

4 Discussion and Conclusions

Early attempts to quantify the global water cycle date back to the early 1900s (Brückner [1905\)](#page-24-4). To date, despite tremendous advances in terms of data and technology, accuracy regarding the components of the global water cycle has not increased accordingly. Ultimately, unquantified uncertainties on remote sensing satellite products (Sheffield et al. [2009\)](#page-31-1), limitations of climate model simulations (Trenberth et al. [2011](#page-31-12)), short and heterogeneous observational data records (Schneider et al. [2017\)](#page-30-16), and the natural fuctuations of water cycle components Markonis et al. ([2018\)](#page-28-27) keep the understanding of the global water cycle ambiguous and human contribution unattributed. Within the twenty-frst century, the paradigm of quantifying the global water cycle has been shifting from identifying the best data source per water cycle component into developing the best way to integrate data from various sources (Aires [2014](#page-23-8)). Therefore, proper statistical tools for uncertainty quantifcation (Papalexiou [2018](#page-29-20)), robust downscaling/disaggregation (Papalexiou et al. [2018](#page-29-21)), along with analysis over multiple scales (Hanel et al. [2017;](#page-26-22) Markonis et al. [2021\)](#page-28-28) are required.

The quest for accurate global water cycle quantifcation gave birth to the Global Energy and Water Exchanges (GEWEX) project. The GEWEX project, formerly known as the

Global Energy and Water Cycle Experiment, started in 1990 and is dedicated to studying the Earth's water and energy cycles (Chahine [1992a](#page-24-27)). GEWEX established a channel for international research collaboration through diferent panels, meetings, and projects. Among the most renowned outcomes, we could mention the work of Trenberth et al. ([2007\)](#page-31-7), which we further discussed in Sect. [2.3](#page-9-0). Speaking of data sets and modeling improvements, GEWEX overlooks eight continental-scale experiments, GEWEX Americas Prediction Project (GAPP; Lawford [1999\)](#page-27-18), Baltic Sea Experiment (BALTEX; Raschke et al. [1998,](#page-29-22) [2001](#page-29-23)), GEWEX Asian Monsoon Experiment (GAME; Yasunari [1994](#page-32-19)), Large Scale Biosphere Atmosphere Experiment in Amazonia (LBA; Marengo [2005\)](#page-28-29), Mackenzie GEWEX Study (MAGS; Stewart et al. [1998\)](#page-31-22), La Plata Basin (LPB; Cavalcanti et al. [2015](#page-24-28)), The African Monsoon Multidisciplinary Analysis (AMMA; Redelsperger et al. [2006\)](#page-30-22), and Murray-Darling Basin (MDB; Evans and McCabe [2010](#page-25-18)). Other than the logistic and political criteria, these sites were selected in order to collect data from diferent climate regimes to assess the global water cycle in a representative manner. The collaborative efort of the international teams involved improved the understanding of regional water balance and feedback processes. The data resulting from the continental-scale experiments are publicly available. Thus, they indirectly started to set up a scientifc framework to quantify the global water cycle and close its budget; the latter was obtained within a 10% non-closure tolerance.

As a rule of thumb, ground observations are regarded as the closest measurements to the actual values. However, it is evident that ground observations sufer from systematic errors, mainly because of diferent environmental and meteorological conditions. For example, the precipitation phase, evaporation from the gauge, and wind drift induce precipitation undercatch on rain gauges (Fuchs et al. [2001](#page-25-19)). The scientifc community is aware that good quality ground observations data represent a cornerstone to quantify the global water cycle, yet we are still unable to deploy a homogeneously distributed global network. Spatial coverage of the Global Precipitation Climatology Centre (GPCC), currently the most comprehensive gauge network available, represents only about 1% of the Earth's surface (assuming no overlap of a 5 km radius per gauge) (Kidd et al. [2017](#page-27-19)). One of the main reasons behind the struggle to deploy a comprehensive network is that ground stations, and ergo observational data records, are extremely geopolitically dependent (Kibler et al. [2014](#page-27-20)). In addition, deploying dense monitoring networks unavoidably imply high operational and maintenance costs and spatial requirements (Saltikoff et al. [2017\)](#page-30-23). Consequently, in many developing countries, ground observational records, if available, tend to have multiple temporal discontinuities or non-standardized data quality check protocols (Walker et al. [2016\)](#page-32-8). Diferent techniques have been used to fll spatiotemporal gaps in observational records. Reconstructing these time series could be achieved using several tools that could be grouped in the following, self-contained inflling (Kemp et al. [1983](#page-27-21); Pappas et al. [2014](#page-29-24)), spatial interpolation (Shepard [1968;](#page-31-23) Young [1992;](#page-32-20) Eischeid et al. [1995](#page-25-20), [2000\)](#page-25-21), quantile mapping (Simolo et al. [2010](#page-31-24); Newman et al. [2015](#page-29-25), [2019;](#page-29-26) Devi et al. [2019](#page-25-22)), and machine learning methods (Dastorani et al. [2010;](#page-25-23) Wambua et al. [2016](#page-32-21)). On a diferent front, there is an opportunity to use data from amateur networks and the internet of things (i.e., big data with large uncertainty) to enhance spatial coverage and spatiotemporal resolution of traditional ground stations via crowdsourcing and the internet. Needless to say, appropriate validation and quality control procedures must be adopted and implemented to fully exploit the potential to provide a valuable source of high spatiotemporal resolution real-time data (Muller et al. [2015](#page-29-27)). As of now, however, the lack of adequate ground-based data and station networks still hampers our ability to monitor the water cycle robustly.

Model simulations can generate past climate, current climate, and climate projections data. Moreover, they are capable to switch anthropogenic forcing on precipitation on and of, while the decoupling of natural and anthropogenic forcing remains a challenge on observational data (Allen and Ingram [2002\)](#page-23-10). However, compared to observational data, various characteristics of global water cycle fuxes, and precipitation, in particular, hold uncertainty (Prein and Pendergrass [2019\)](#page-29-28). The simulated projections' temporal length appears to infuence precipitation trends, e.g., variability in precipitation estimates are indistinguishable from the noise of internal variability in 20-year or longer runs (Hawkins et al. [2016\)](#page-26-23). Specifcations difer from model to model, but in general, recycling of moisture is too large, and the lifetime of moisture is too short across most models, inducing premature precipitation (Trenberth et al. [2011\)](#page-31-12). Also, inaccurate convective parameterizations evidenced that models overestimate precipitation frequency and underestimate its intensity (Trenberth et al. [2017\)](#page-31-25). Analysis focusing on convective precipitation highlighted that its model representation is strongly dependent on the model depiction of cloud microphysics and cloud spatiotemporal variability (Zhao et al. [2016](#page-32-22)). There is a threefold spread in mean precipitation change with global temperature $(1 - 3\% K^{-1})$, and model simulations showed that there is a correlation between an increase in precipitation extremes and an increase in model resolution, precipitation extremes at the same time showed an anticorrelation with changes in light-moderate precipitation (Thackeray et al. [2018](#page-31-26)). Furthermore, both the spread and magnitude of change in extreme precipitation vastly exceed those of mean precipitation (4 − 10% *K*[−]¹) (Kharin et al. [2013\)](#page-27-22). Last but not least, despite the known link between the energy and water global cycles, solar dimming and brightening (the efect of aerosols) are not well represented or sometimes not even considered at all in models; thus, model simulations fail to reproduce variability in the global water cycle intensity (Wild and Liepert [2010\)](#page-32-23).

Satellite remote sensing observations, like models, are limited by their design. Both the orbit they follow and the instrument type (i.e., active or passive) infuence global water cycle components' monitoring. The satellite's orbit would delimit its spatiotemporal resolution or coverage. In general, a satellite with high spatial resolution comes with coarse temporal resolution and vice-versa, and high spatiotemporal resolution comes with limited coverage. It has been shown that estimates from active sensors can considerably vary from passive sensor ones, yet they complement each other (Petković and Kummerow [2017](#page-29-29)). In addition, similarly to ground observations, satellite remote sensing has to deal with diferent meteorological conditions. For instance, satellite-based global water cycle estimates accuracy is afected by cloud-top refectance and thermal radiance, making uncertainty larger during the winter or in dry climates (Kummerow et al. [2004\)](#page-27-23). While satellites can monitor the water cycle at the global scale and cover regions inaccessible by ground stations, they still have to tackle the problems involved in complex topography regions. In some cases, the relative biases reach as much as 300% for precipitation estimates (Fekete et al. [2004\)](#page-25-24). Further complications arise from the unique spatiotemporal characteristics of diferent remotely sensed global water cycle components, making it impossible to assess the water budget without some sort of prior downscaling or integration (Sheffield et al. [2018\)](#page-31-27). E.g., TMPA's precipitation at 25 km every three hours (Hufman et al. [2007\)](#page-26-9), MODIS' evapotranspiration at 1 km daily (Mu et al. [2007](#page-28-23)), and GRACE's total water storage at ∼ 500 km every 30 days(Tapley et al. [2004](#page-31-6)). Despite all the issues mentioned above, satellite products continue to be the most widely used sources to monitor global water cycle components due to their comprehensive spatial coverage.

It is clear that no global water cycle data source is without fail, and in some cases, one data source strengths cover for other weaknesses. It is typical for satellite-based measurements and model simulations to use ground-based data for validation, calibration, and enhancement purposes. Along the same line, model simulations additionally assimilate satellite-based observations for the above plus for reanalysis. In contrast to the top-down estimation approach used in satellite remote sensing, a bottom-up approach, referred to as reverse hydrology, has been recently proposed (Ciabatta et al. [2020](#page-24-29)). A physically based selection of surface explanatory variables, like soil moisture, vegetation cover, and topography, is expected to preserve process dynamics and interlinkages within data sets that remain unresolved in conventional statistical downscaling bias-correction methods (Wehbe et al. [2020](#page-32-24)). It is of utmost importance that the research community strives to improve ground observations, model simulations, and satellite remote sensing measurements individually because more accurate and robust individual data sources will subsequently refne the outcome of multi-source integration. Hence, a three-way integration of satellite remote sensing, model reanalysis, and ground-based measurements, as discussed in Sect. [2.4](#page-11-0), is widely acknowledged as the current best practice, particularly when leveraging machine learning tools to handle large data sets.

Acknowledgements This work was supported by the Faculty of Environmental Sciences, Czech University of Life Sciences Prague internal Grant 2020B0001 "A multiscale framework for data analysis of global precipitation". The data compiled herein and the R code for the fgures are publicly available at [https://github.](https://github.com/MiRoVaGo/chronology_gwc) [com/MiRoVaGo/chronology_gwc](https://github.com/MiRoVaGo/chronology_gwc).

Declarations

Confict of interest The authors declare that they have no confict of interest.

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